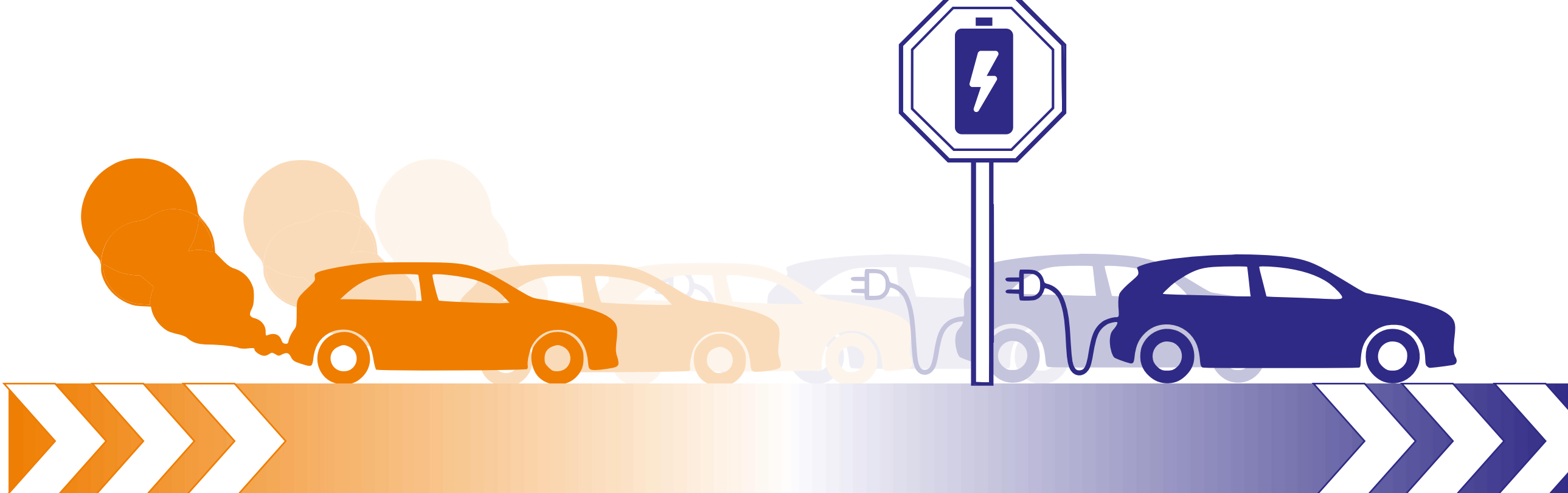


# A machine learning based rolling resistance prediction model for Electric Vehicles

Candidate: GRAVANTE Gerardo<sup>1</sup>, [gerardo.gravante@univ-eiffel.fr](mailto:gerardo.gravante@univ-eiffel.fr)  
Supervisors: CEREZO Véronique<sup>1</sup>, SANTOS João<sup>2</sup>

<sup>1</sup>AME-EASE, University Gustave Eiffel, <sup>2</sup>Department of Civil Engineering and Management (CEM), University of Twente

## Introduction



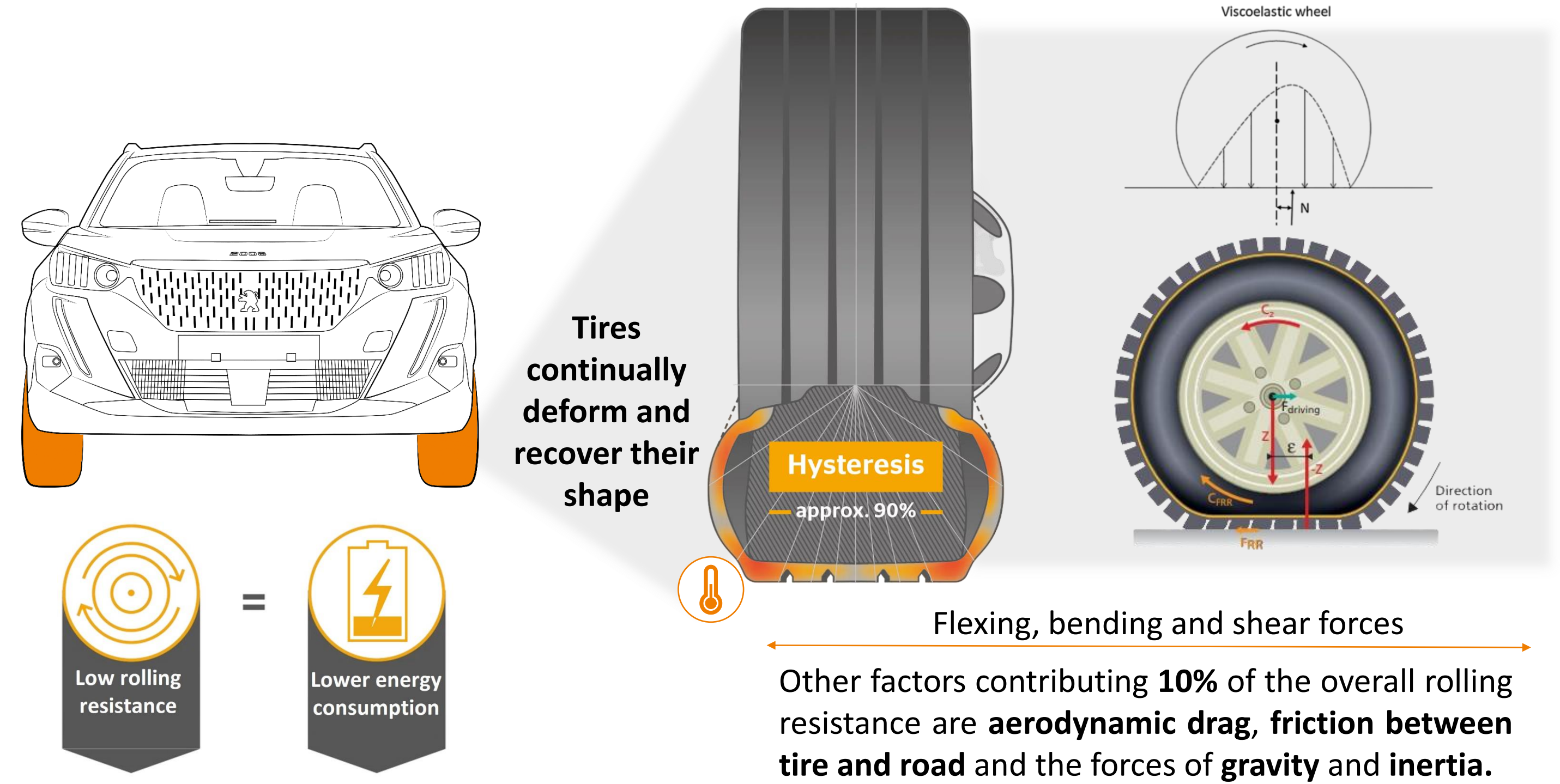
Rolling Resistance accounts for up to **30%** of a vehicle's energy consumption [1].

**Key Factors** [2]

- Pavement's** structural and functional characteristics (roughness, texture, stiffness, temperature).
- Tires'** structural and performance properties (tread characteristics, temperature, pressure).
- Vehicle's** structural and performance properties (suspensions, load, load distribution, speed).

## What is Rolling Resistance?

The energy consumed by a tire per unit of distance covered [3].



Tires continually deform and recover their shape

Hysteresis approx. 90%

Flexing, bending and shear forces

Other factors contributing 10% of the overall rolling resistance are aerodynamic drag, friction between tire and road and the forces of gravity and inertia.

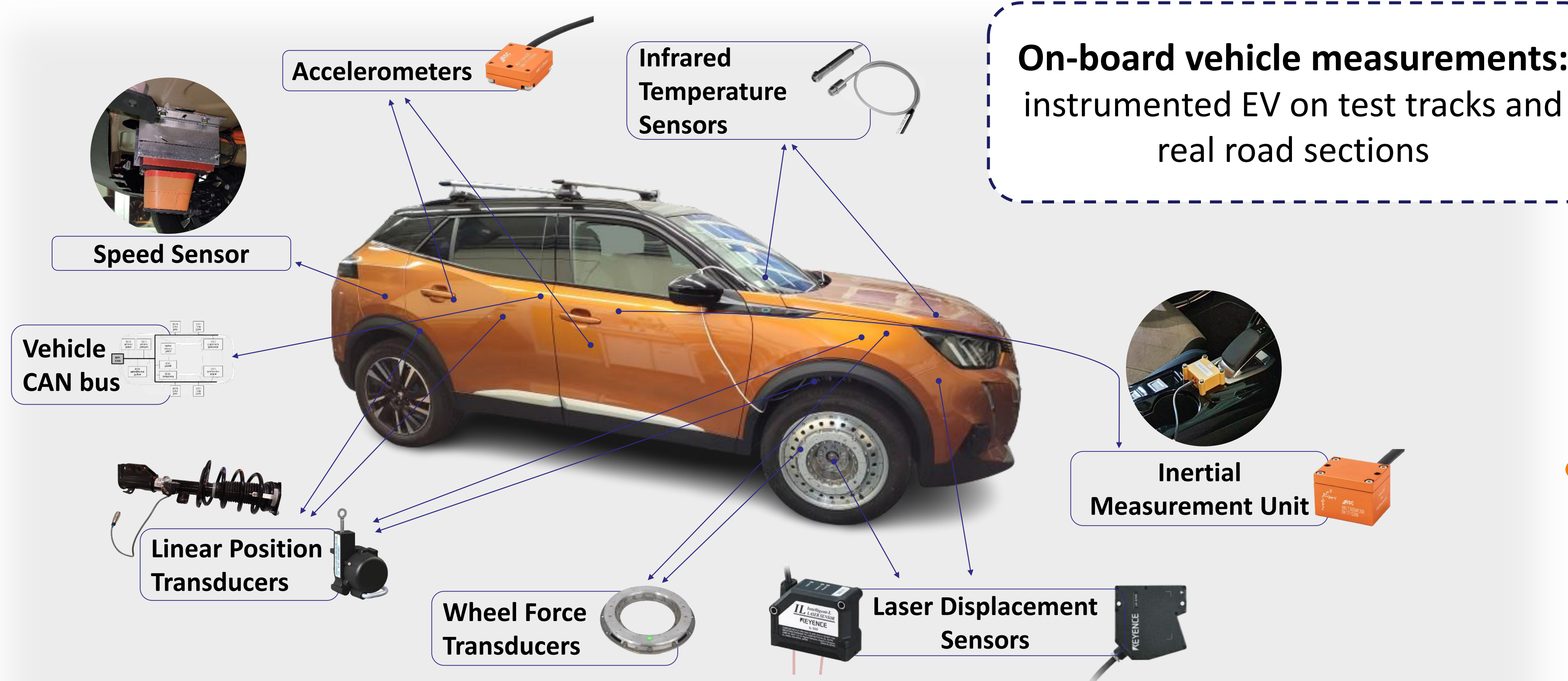
## Knowledge GAP

- Few studies on rolling resistance concerning Electric Vehicles (EVs).
- Effect of increased EVs' torque and weight on rolling resistance.
- No models available to estimate rolling resistance for EVs.

## Objectives

- To develop a data-driven rolling resistance prediction model for EVs.
- To assess the potential of Machine Learning for rolling resistance estimations.

## Methodology



**On-board vehicle measurements:** instrumented EV on test tracks and real road sections

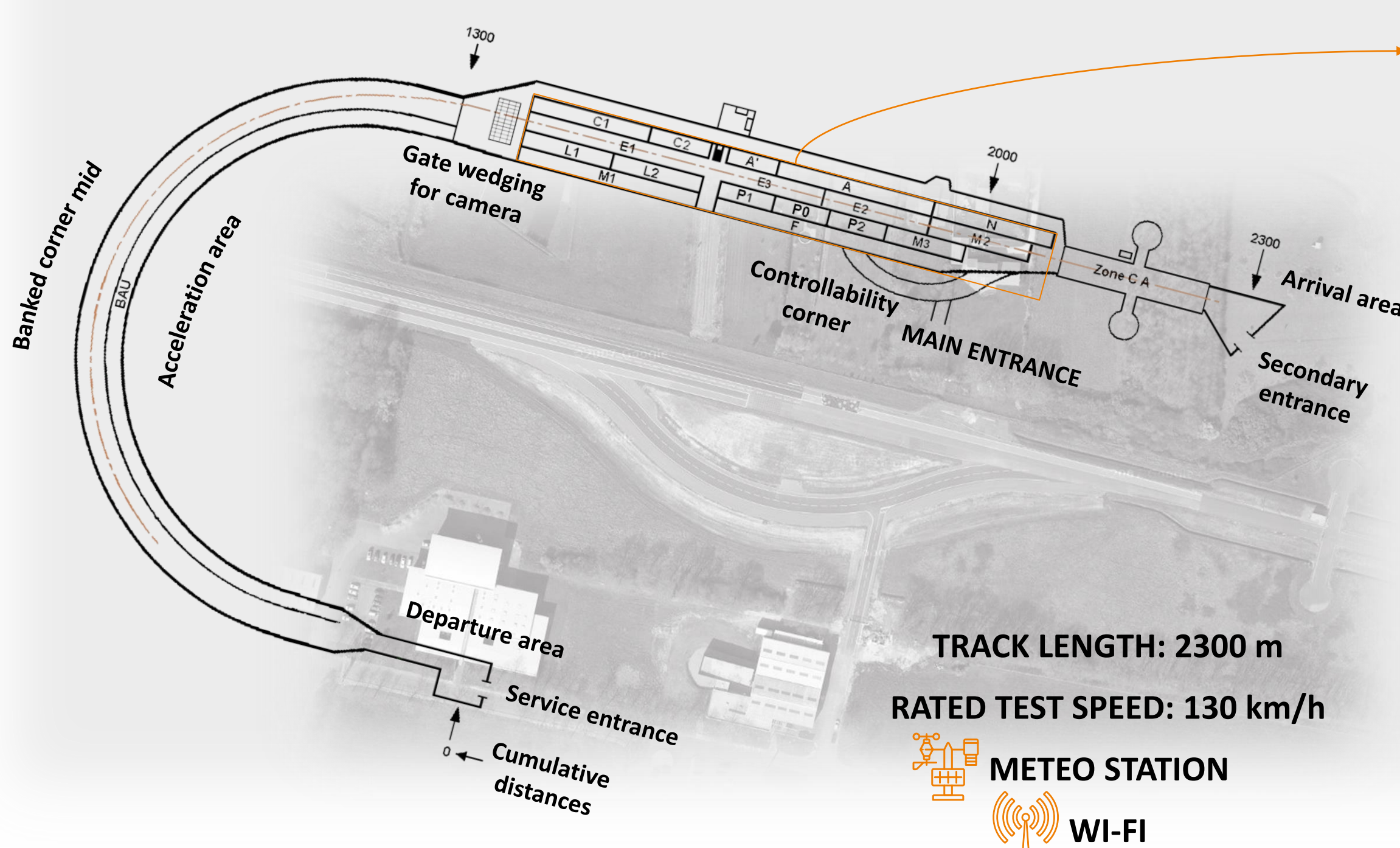
Rolling resistance forces in the tire-road contact area

Tires temperature and deformation, suspensions behavior

Pavement characteristics (IRI, MPD)

Vehicle speeds and accelerations

**Training of a Machine Learning model:** multi-step approach



TEST BOARDS AREA: 700 m

TRACK LENGTH: 2300 m  
RATED TEST SPEED: 130 km/h

A'	Coarse surface dressing 8/10
A	Porous asphalt concrete 0/6
N	Porous cement concrete
E1	Dense asphalt concrete 0/10 (new)
E2	Dense asphalt concrete (old)
M2	Very thin asphalt concrete 0/6, cl.2
L1	Epoxy resin (smooth)
L2	Sand asphalt 0/4
M1	Very thin asphalt concrete 0/10, cl.1
F	Colgrip surface dressing 1/3 bauxite

**DATA MINING**

**DATA COLLECTION**

- Test plans including variations in:
  - Vehicle speed.
  - Road pavement sections.
  - Tire inflation pressure.

**DATA PREPARATION**

- Data filtering.
- Data cleansing.
- Data transforming.
- Data reduction.
- Data splitting.

**MODEL DEVELOPMENT**

**MODEL TRAINING**

- Algorithm selection.
- Learning through training dataset.

**MODEL EVALUATION**

- Validation through testing dataset.

**MODEL IMPROVEMENT**

- Tuning algorithm parameters.
- Monitoring and maintenance.

## Expected Outcomes

- Outdoor testing procedure to measure rolling resistance for EVs.
- Rolling resistance prediction model based on vehicle's dynamic states, tire features and pavement characteristics data.

## References

- [1] U. Sandberg, U. Hammarström, R. Karlsson, J. A. Ejsmont and A. Bergiers, "MIRIAM: Rolling resistance-Basic information and State-of-the-Art on measurement methods". 2011.
- [2] Cerezo V., Santos J., Bouteldja M., Potier X. "Relationship between driving conditions, pavement characteristics and rolling resistance". In : The 9th Symposium on Pavement Surface Characteristics (SURF2022). Milano, Italy, 2022.
- [3] Michelin, "Le pneu Résistance au roulement," 2003.

